

**Practice test #3 Answer key**

1. In order to check that a transformation is linear you have to check the two properties,  $T((x_1, y_1) + (x_2, y_2)) = T(x_1, y_1) + T(x_2, y_2)$  and  $T(c(x, y)) = cT(x, y)$ .

Since the transformation is not linear, it is sufficient to show that one of the properties fails to be satisfied for a particular choice of values of  $x, y$  and/or  $c$ .

In particular, if  $x=y=0$ , and  $c=2$ , the second property says that  $T(2(0,0)) = 2T(0,0)$ . But  $T(2(0,0)) = T(0,0) = 5$ , whereas  $2T(0,0) = 10$ , proving that the transformation is not linear.

2. The transformation is not linear. Indeed, if we consider

$$T(2(x, y)) = T((2x, 2y)) = (2x, 1), \text{ whereas } 2T((x, y)) = 2(x, 1) = (2x, 2) \neq T(2(x, y)).$$

3. (a) It is pretty obvious what the standard matrix should be, but to follow the directions of the problem we will find the values of  $T$  applied to the standard basis vectors. We have

$$T(1,0) = (1,0), \text{ and } T(0,1) = (0,-1), \text{ and therefore } T = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}.$$

(b) Notice that  $T : R^4 \rightarrow R$ , and as before we get  $T = [4 \ 6 \ 7 \ 8]$ .

(c)  $T : R^2 \rightarrow R^3$ . We need to use the vectors of the basis now. Let

$e_1 = (1,0)$ , and  $e_2 = (0,1)$ . We have  $(-1,1) = -e_1 + e_2$ , and  $(2,-1) = 2e_1 - e_2$ . Applying the linearity of the transformation, we have:

$$\begin{cases} T(-1,1) = -T(e_1) + T(e_2) = (3,0,-1) \\ T(2,-1) = 2T(e_1) - T(e_2) = (0,-2,4). \end{cases} \text{ We may now solve the system by adding the two}$$

equations to obtain  $T(e_1) = (3,-2,3)$ , and then by substituting,  $T(e_2) = (6,-2,2)$ .

$$\text{Therefore, } T = \begin{bmatrix} 3 & 6 \\ -2 & -2 \\ 3 & 2 \end{bmatrix}.$$

4. We have  $T = \begin{bmatrix} 3 & 3 \\ -1 & -1 \end{bmatrix}$ , and since  $\det(T)=0$  it follows that  $T$  is not one-to-one. Since

$\det(T)=0$ , it also follows that the range of  $T$  cannot be  $R^2$ . In order to find a vector that is not in the range, notice that the vectors  $\mathbf{w}$  in the range of  $T$  have the property that  $w_1 = -3w_2$ . Therefore, if we take the vector  $\mathbf{w}=(0,1)$ , there is not vector  $(x,y)$  such that  $T(x, y) = (0,1)$ .

5. The equation of the line through  $(4,1)$  and the origin is  $x-4y=0$ , so a possible matrix is  $A = \begin{bmatrix} 1 & -4 \\ 2 & -8 \end{bmatrix}$ .

6. We begin by checking whether the vectors are linearly independent. Since  $\dim(P_3) = 4$ , if we prove linear independence automatically the vectors will span the

space. Let  $c_1(t^3 - 2t^2 + 1) + c_2(t^2 - 4) + c_3(t^3 + 2t) + c_4 5t = 0$ . Then if we group on power  $s$  of  $t$ , all coefficients must be zero. We get:

$$\begin{cases} c_1 + c_3 = 0 \\ -2c_1 + c_2 = 0 \\ 2c_3 + c_4 = 0 \\ c_1 - 4c_2 = 0 \end{cases}$$

The matrix of the above system has a non-zero determinant, and therefore the system has only the trivial solution. Therefore,  $c_1 = c_2 = c_3 = c_4 = 0$  and the vectors are linearly independent. Since the dimension of the space is 4 and we have 4 linearly independent vectors, they form a basis.

7. It can be checked that the set is a subspace of  $R^3$ . If we denote  $x = 2s - t, y = s, z = t$  we can see that  $W$  is the set of points satisfying  $x = 2y - z$ , or  $x - 2y + z = 0$ , which is a plane going through the origin. To find a basis in this subspace we write:

$$(2s - t, s, t) = s(2, 1, 0) + t(-1, 0, 1)$$

Then the vectors  $(2, 1, 0), (-1, 0, 1)$  span  $W$ . Moreover, they are linearly independent since

$$s(2, 1, 0) + t(-1, 0, 1) = (0, 0, 0) \Rightarrow s = t = 0$$

Therefore they are a basis in  $W$ .

8. To find a basis in  $R^2$  that includes  $(1, 1)$  it is enough to find a vector which is not a multiple of  $(1, 1)$ . Any such vector will do. Take for example  $(2, 1)$ . Then we have two linearly independent vectors,  $(1, 1), (2, 1)$  and since  $\dim(R^2) = 2$ , the two vectors are a basis.

9. We will use the linearity of the operator to determine the value of  $T$  on the standard basis vectors,  $T(1, 0)$ , and  $T(0, 1)$ . Refer to the standard basis vectors as  $e_1, e_2$ . We have:

$$T(1, 2) = T(e_1 + 2e_2) = T(e_1) + 2T(e_2) = (-2, 3)$$

$$T(1, -1) = T(e_1 - e_2) = T(e_1) - T(e_2) = (5, 2)$$

We can solve the above system to obtain:  $3T(e_2) = (-7, 1), 3T(e_1) = (8, 7)$ . Therefore

$$T = \frac{1}{3} \begin{bmatrix} 8 & -7 \\ 7 & 1 \end{bmatrix}, \text{ and } T \begin{pmatrix} 7 \\ 5 \end{pmatrix} = \frac{1}{3} \begin{bmatrix} 8 & -7 \\ 7 & 1 \end{bmatrix} \begin{bmatrix} 7 \\ 5 \end{bmatrix} = \begin{bmatrix} 7 \\ 18 \end{bmatrix}.$$

10. a) Let  $u_1 = (x_1, y_1), u_2 = (x_2, y_2) \in R^2, c_1, c_2 \in R$ . We have

$$\begin{aligned} T(c_1 u_1 + c_2 u_2) &= (c_1 x_1 + c_2 x_2 + c_1 y_1 + c_2 y_2, c_1 x_1 + c_2 x_2 - c_1 y_1 - c_2 y_2, 3(c_1 x_1 + c_2 x_2) + 2(c_1 y_1 + c_2 y_2)) \\ &= c_1(x_1 + y_1, x_1 - y_1, 3x_1 + 2y_1) + c_2(x_2 + y_2, x_2 - y_2, 3x_2 + 2y_2) = c_1 T(u_1) + c_2 T(u_2) \end{aligned}$$

so the transformation is linear.

b) In order to decide whether  $T$  is one-to-one we need to see whether  $T(x, y) = (0, 0, 0)$  has only the trivial solution  $(x, y) = (0, 0)$ . We write the matrix of the transformation and reduce it to its reduced row echelon form:

$T = \begin{bmatrix} 1 & 1 \\ 1 & -1 \\ 3 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$ . Since the matrix has two leading ones, and we solve for two

unknowns, the system will have only the trivial solution, and therefore the transformation is one-to-one.

c) Let now  $(w_1, w_2, w_3) \in \mathbb{R}^3$ . We need to see whether there exists  $(x, y) \in \mathbb{R}^2$  such that  $T(x, y) = (w_1, w_2, w_3)$ . We write the augmented matrix of the system and reduce it:

$$\begin{bmatrix} 1 & 1 & w_1 \\ 1 & -1 & w_2 \\ 3 & 2 & w_3 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & w_1 \\ 0 & -2 & w_2 - w_1 \\ 0 & -1 & w_3 - 3w_1 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & w_1 \\ 0 & 1 & -\frac{1}{2}(w_2 - w_1) \\ 0 & 0 & w_3 - 3w_1 - \frac{1}{2}(w_2 - w_1) \end{bmatrix}$$

The system will be consistent if and only if  $w_3 - 3w_1 - \frac{1}{2}(w_2 - w_1) = 0, 2w_3 - 5w_1 - w_2 = 0$ .

A vector that is not in the range(T) is  $(1, 0, 1)$ .

11. Of course, since one vector is a multiple of the other the two vectors cannot span  $\mathbb{R}^2$ . We will actually find a vector in  $\mathbb{R}^2$  that is not in  $\text{span}\{(1, 1), (-2, -2)\}$ . Consider the vector  $(1, 0)$ . If it were in the subspace spanned by the two given vectors, then there must exist  $c_1, c_2$  such that  $c_1(1, 1) + c_2(-2, -2) = (1, 0)$ . But if we write the system corresponding to this vector equation we obtain  $c_1 - 2c_2 = 1 = 0$ . Therefore there do not exist such scalars, and thus  $(1, 0)$  is not in  $\text{span}\{(1, 1), (-2, -2)\}$ .